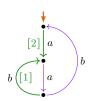
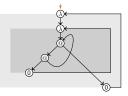
## Modeling Terms by Graphs with Structure Constraints (Two Illustrations)

#### Clemens Grabmayer



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Overview

LEE-witnesses: graph labelings based on a loop-condition LEE

- 2. Maximal sharing of functional programs
  - higher-order  $\lambda$ -term graphs

#### Overview

- 1. Process interpretation of regular expressions
  - Milner's questions, known results
  - structure-constrained process graphs:
    - ▶ LEE-witnesses: graph labelings based on a loop-condition LEE
    - preservation under bisimulation collapse
  - readback: from graph labelings to regular expressions
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    - first-order  $\lambda$ -term graphs
    - $\lambda$ -NFAs, and  $\lambda$ -DFAs
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- Comparison results

 Regular expressions under process semantics (bisimilarity ↔)

 Given: process graph interpretation [[·]]<sub>P</sub>, studied under ↔

 ▶ not closed under →, and ↔, modulo ↔ incomplete

#### $\lambda\text{-calculus}$ with letrec under unfolding semantics

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*Not available:* term graph interpretation that is studied under  $\Leftrightarrow$ 

 graph representations used by compilers were not intended for use under ↔

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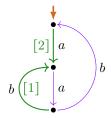
*Not available:* term graph interpretation that is studied under  $\Leftrightarrow$ 

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Desired: term graph interpretation that:

- natural correspondence with terms in  $\lambda_{ ext{letrec}}$
- supports compactification under  $\leq$
- efficient translation and readback

(current work with Wan Fokkink)



### **Regular Expressions**

#### Definition

The set Reg(A) of regular expressions over alphabet A is defined by the grammar:

$$e, f ::= 0 \mid 1 \mid a \mid (e+f) \mid (e \cdot f) \mid (e^{\star})$$
 (for  $a \in A$ ).

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The set Reg(A) of regular expressions over alphabet A is defined by the grammar:

$$e, f ::= 0 | 1 | a | (e + f) | (e \cdot f) | (e^*)$$
 (for  $a \in A$ ).

Note, here:

- ▶ symbol 0 instead of Ø
- ▶ symbol 1 used (often dropped, definable as 0<sup>\*</sup>)
- no complementation operation  $\overline{e}$ 
  - is not expressible under language interpretation

O C-des PI pi Mil Milner's Qs loop-elim LEE LEE-witness collapse readback 1r-less line-up MS interpret collapse readback c d lit C-res

## Language interpretation $\llbracket \cdot \rrbracket_L$ (S.C. Kleene, 1951)

$$\begin{array}{cccc} \mathbf{0} & \stackrel{\left[ \cdot \right]_{L}}{\mapsto} & \text{empty language } \varnothing \\ \mathbf{1} & \stackrel{\left[ \cdot \right]_{L}}{\mapsto} & \{\epsilon\} & (\epsilon \text{ the empty word}) \\ a & \stackrel{\left[ \cdot \right]_{L}}{\mapsto} & \{a\} \end{array}$$

## Language interpretation $\llbracket \cdot \rrbracket_L$ (S.C. Kleene, 1951)

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$$a \xrightarrow{\mathbb{I}^{\cdot}\mathbb{J}_L} \{a\}$$

$$\begin{array}{ccc} e+f & \stackrel{\llbracket\cdot\rrbracket_L}{\longrightarrow} & \text{union of } \llbracket e \rrbracket_L \text{ and } \llbracket f \rrbracket_L \\ e \cdot f & \stackrel{\llbracket\cdot\rrbracket_L}{\longrightarrow} & \text{element-wise concatenation of } \llbracket e \rrbracket_L \text{ and } \llbracket f \rrbracket_L \\ e^* & \stackrel{\llbracket\cdot\rrbracket_L}{\longrightarrow} & \text{set of words formed by concatenating words in } \llbracket e \rrbracket_L \end{array}$$

# Process interpretation $\llbracket \cdot \rrbracket_P$ (R. Milner, 1984)

**т** т

$$0 \stackrel{\llbracket \cdot \rrbracket_P}{\longmapsto} \text{ deadlock } \delta, \text{ no termination}$$

$$1 \stackrel{\llbracket \cdot \rrbracket_P}{\longmapsto} \text{ empty process } \epsilon, \text{ then terminate}$$

$$a \xrightarrow{\|\cdot\|_P}$$
 atomic action  $a$ , then terminate

## Process interpretation $\llbracket \cdot \rrbracket_{P}$ (R. Milner, 1984)

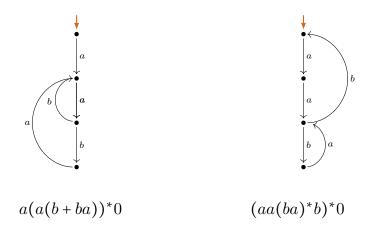
. .

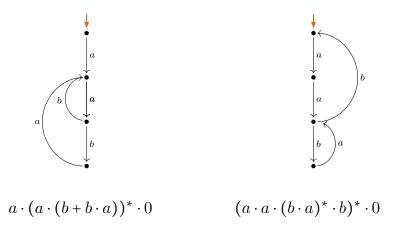
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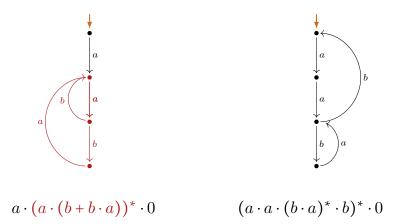
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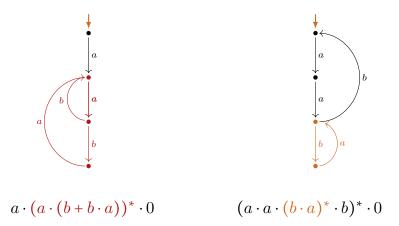
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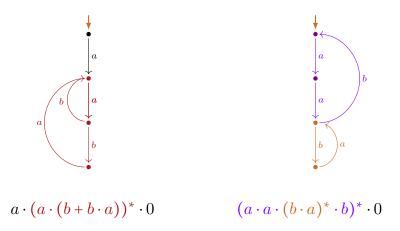
$$\begin{array}{ccc} e+f & \stackrel{\llbracket \cdot \rrbracket_P}{\longmapsto} & \text{alternative composition between } \llbracket e \rrbracket_P & \text{and } \llbracket f \rrbracket_P \\ e \cdot f & \stackrel{\llbracket \cdot \rrbracket_P}{\longmapsto} & \text{sequential composition of } \llbracket e \rrbracket_P & \text{and } \llbracket f \rrbracket_P \\ e^* & \stackrel{\llbracket \cdot \rrbracket_P}{\longmapsto} & \text{unbounded iteration of } \llbracket e \rrbracket_P, \text{ option to terminate} \end{array}$$

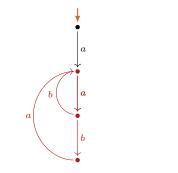


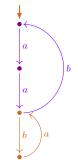






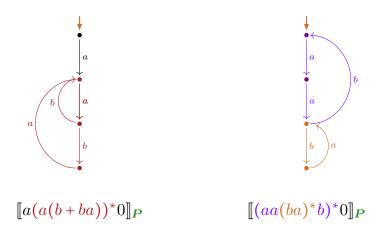


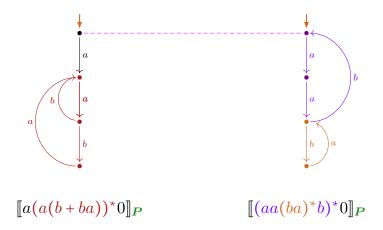


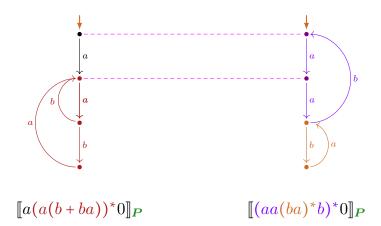


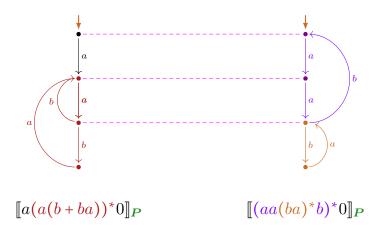
 $\llbracket a \cdot (a \cdot (b + b \cdot a))^* \cdot 0 \rrbracket_{\mathbf{P}}$ 

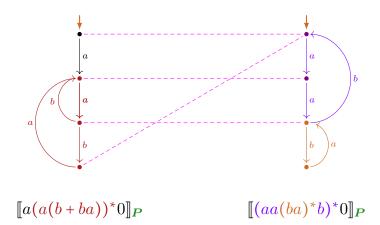
 $\llbracket (a \cdot a \cdot (b \cdot a)^* \cdot b)^* \cdot 0 \rrbracket_{P}$ 

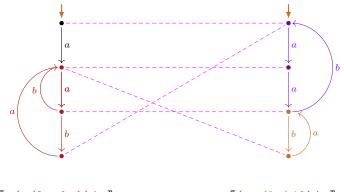






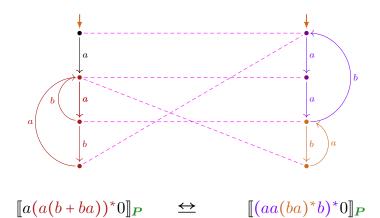


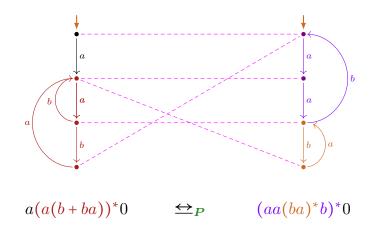




 $\llbracket a(a(b+ba))^*0 \rrbracket_{\mathbf{P}}$ 

 $\llbracket (aa(ba)^*b)^*0 \rrbracket_{\boldsymbol{P}}$ 





Definition

A process graph over actions in A is a tuple  $G = \langle V, v_s, T, E \rangle$  where:

- V is a set of vertices,
- $v_s \in V$  is the *start vertex*,
- $T \subseteq V \times A \times V$  the set of *transitions*,
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With the finiteness restriction, process graphs can be viewed as:

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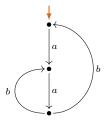
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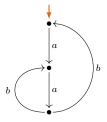
that are studied under bisimulation, not under language equivalence.

#### Antimirov (1996): NFA-definition of $\llbracket \cdot \rrbracket_P$ via partial derivatives.

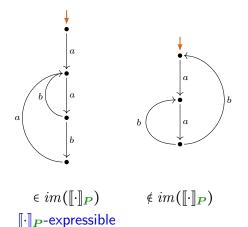
## Expressible process graphs (under bisimulation $\Leftrightarrow$ )

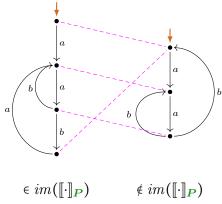


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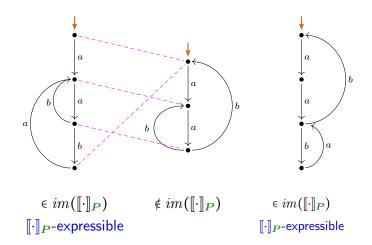


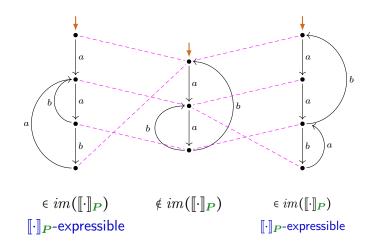
 $\notin im(\llbracket \cdot \rrbracket_{\boldsymbol{P}})$ 

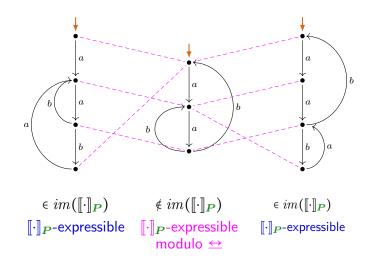




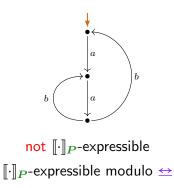
 $\llbracket \cdot \rrbracket_{P}$ -expressible



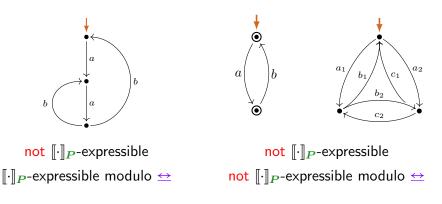




▶ Not every finite-state process is [[·]]<sub>P</sub>-expressible.

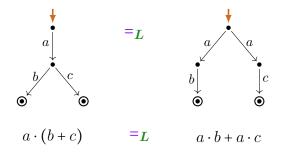


- ▶ Not every finite-state process is **[**.]<sub>P</sub>-expressible.
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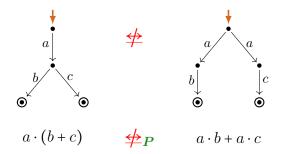


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### Salomaa's axiomatization of $=_L$ (products commuted)

#### Axioms :

$$\frac{e = f \cdot e + g}{e = f^* \cdot g} \text{ FIX } (\text{if } \{\epsilon\} \notin \llbracket f \rrbracket_L)$$
non-empty-word
property

### Sound and unsound axioms with respect to $\leq_P$

#### Axioms :

(B1)	e + (f + g) = (e + f) + g	$(B7)  e \cdot 1 = e$
(B2)	$(e \cdot f) \cdot g = e \cdot (f \cdot g)$	$(B8)  e \cdot 0 = 0$
(B3)	e + f = f + e	(B9) $e + 0 = e$
(B4)	$(e+f) \cdot g = e \cdot g + f \cdot g$	(B10) $e^* = 1 + e \cdot e^*$
(B5)	$e \cdot (f + g) = e \cdot f + e \cdot g$	(B11) $e^* = (1+e)^*$
(B6)	e + e = e	

Inference rules : equational logic plus

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## Milner's adaptation for $\leq_P$ (Mil = Mil<sup>-</sup> + RSP\*)

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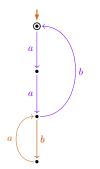
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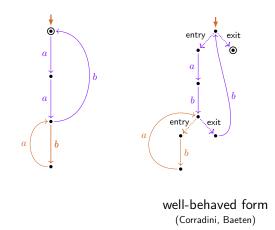
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  - ▶ Mil<sup>-</sup> + one of two stronger rules (than RSP<sup>\*</sup>) is complete (*G*, 2006)
    - with a coinductive rule (based on Antimirov's partial derivatives)
    - with a unique solvability principle USP

# Well-behaved form, looping palm trees



#### $\llbracket (aa(ba)^*b)^* \rrbracket_P$

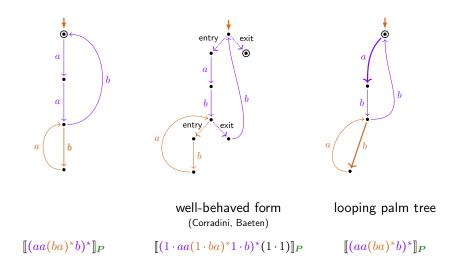
## Well-behaved form, looping palm trees



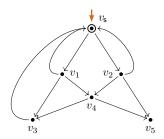
 $\llbracket (aa(ba)^*b)^* \rrbracket_P$ 

 $[(1 \cdot aa(1 \cdot ba)^* 1 \cdot b)^* (1 \cdot 1)]_P$ 

## Well-behaved form, looping palm trees



Definition		
A process graph is a loop chart if:		
L-1.		
L-2.		
L-3.		



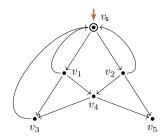
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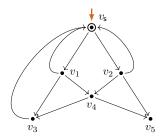
L-2.

L-3.



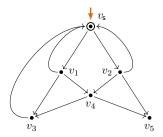
#### Definition

- L-1. There is an infinite path from the start vertex.
- L-2. Every infinite path from the start vertex returns to it.
- L-3.



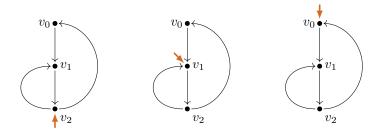
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- L-2. Every infinite path from the start vertex returns to it.
- L-3. Termination is only possible at the start vertex.



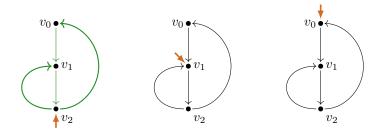
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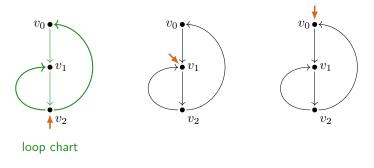
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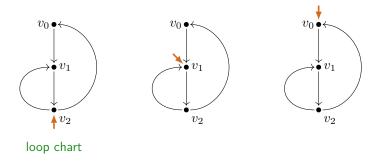
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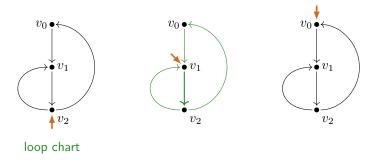
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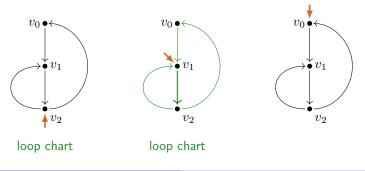
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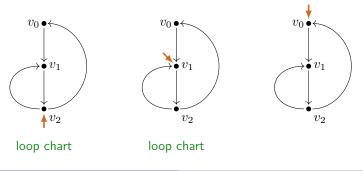
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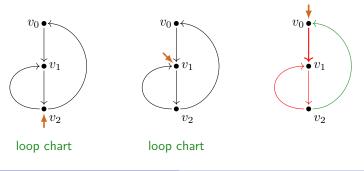
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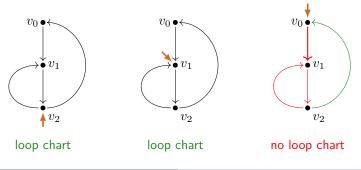
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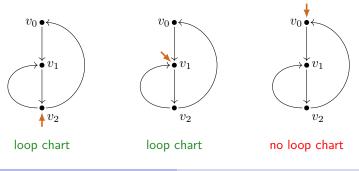
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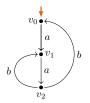
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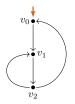


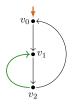
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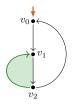
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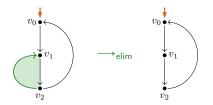


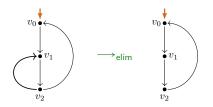


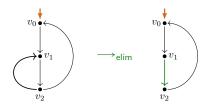


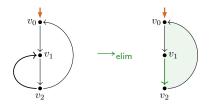


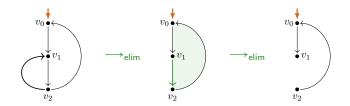


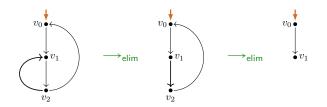


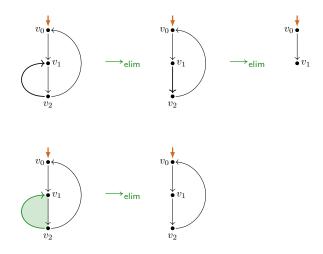


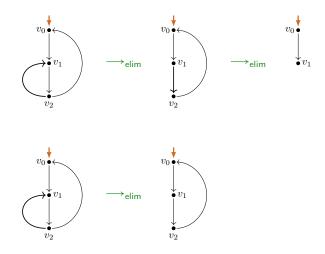


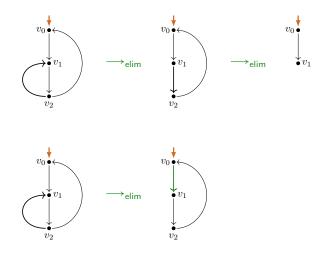


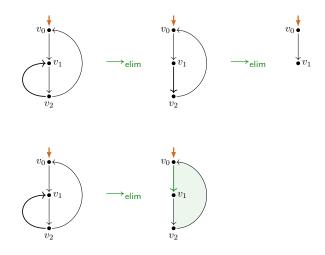


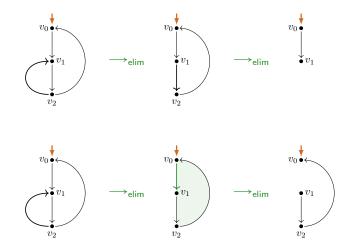


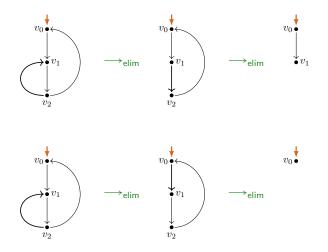


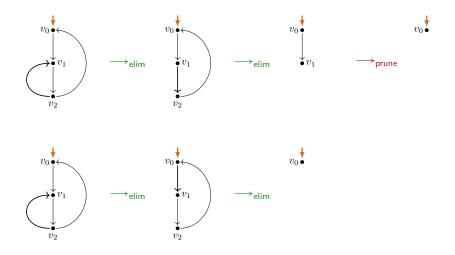












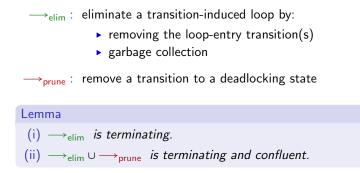
#### Loop elimination, and properties

# $\rightarrow_{\mathsf{elim}}$ : eliminate a transition-induced loop by:

- removing the loop-entry transition(s)
- garbage collection

→<sub>prune</sub> : remove a transition to a deadlocking state

#### Loop elimination, and properties







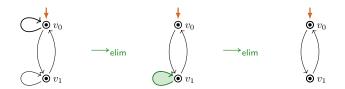


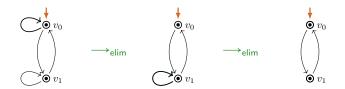


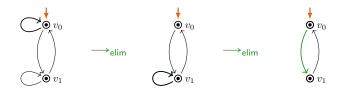


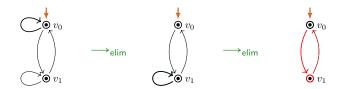


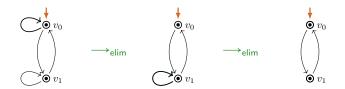


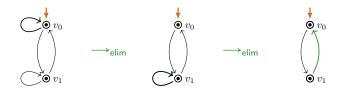


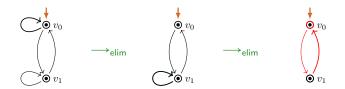


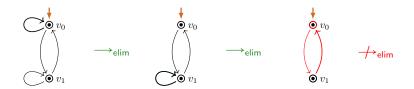


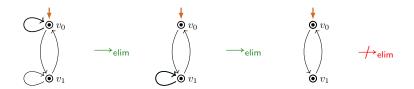


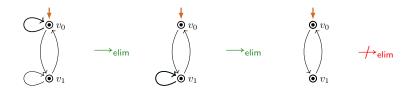


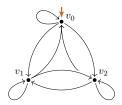


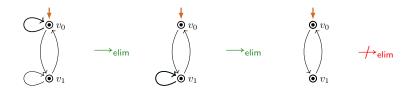


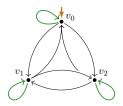


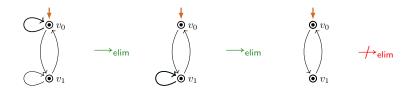


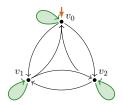


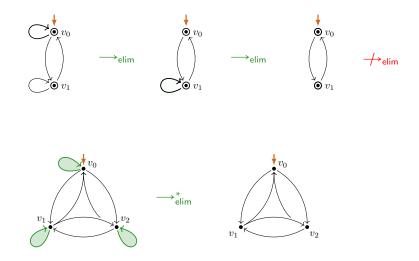


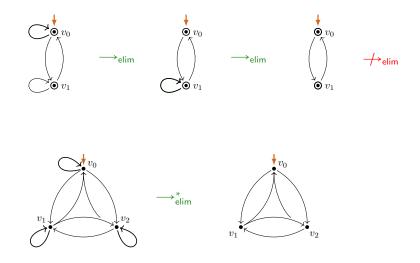


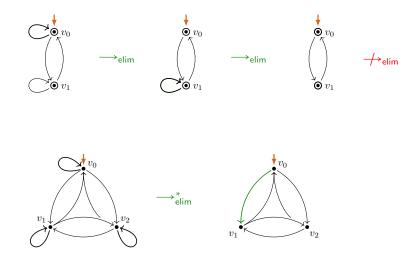


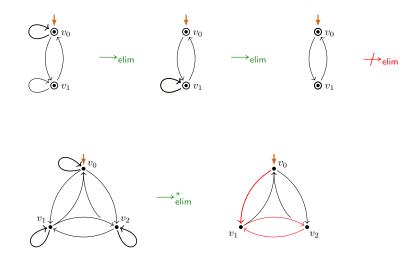


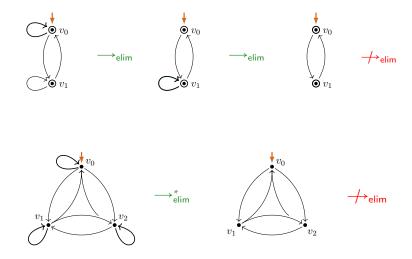












#### Definition

A process graph G satisfies LEE (loop existence and elimination) if:

$$\exists G_0 \left( G \longrightarrow_{\mathsf{elim}}^* G_0 \not\longrightarrow_{\mathsf{elim}} \right.$$

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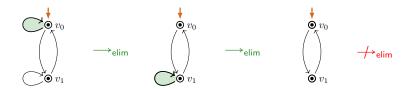
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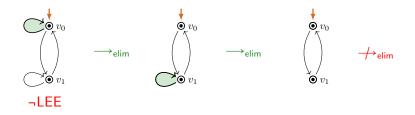
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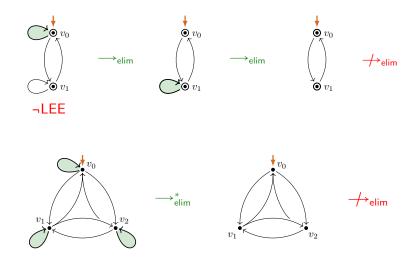
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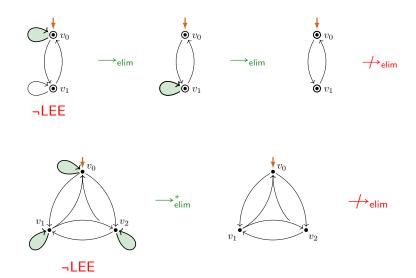
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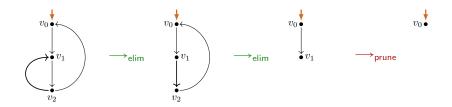




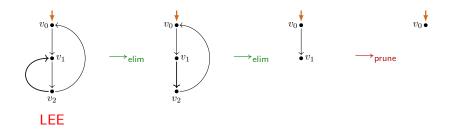


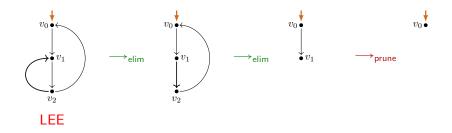


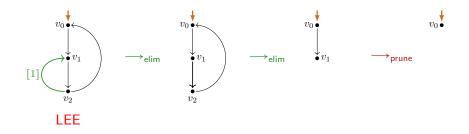
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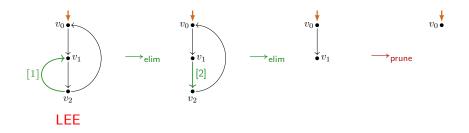


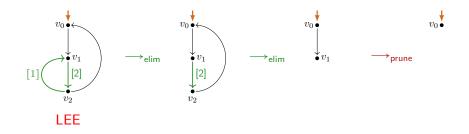
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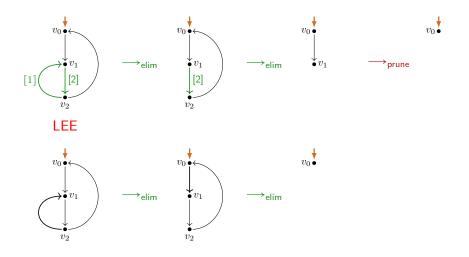


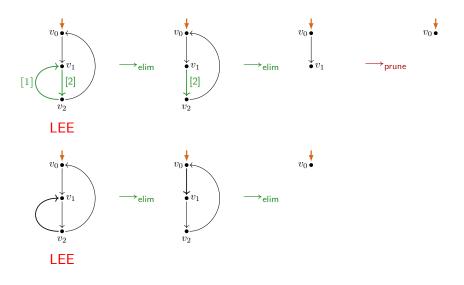


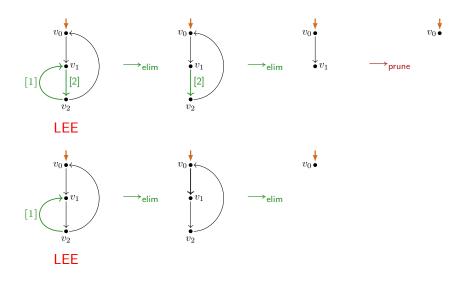


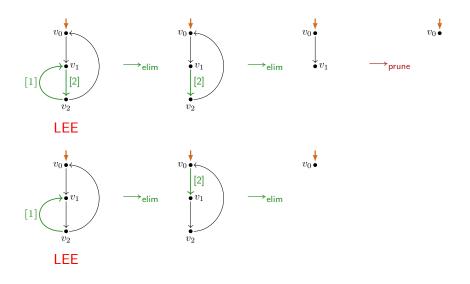


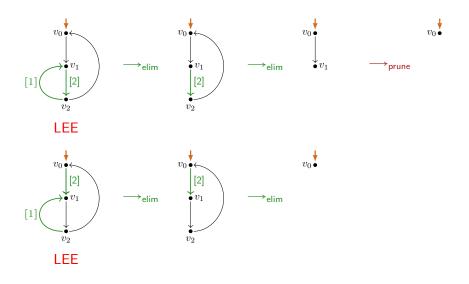


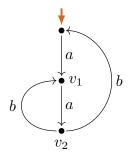




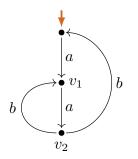




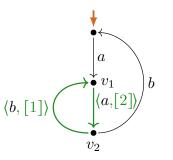




loop-branch labeling: marking transitions  $\xrightarrow{a}$  as:

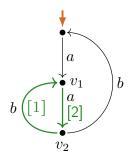


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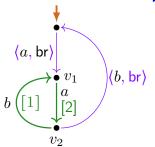
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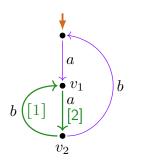
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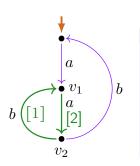
• branch steps 
$$\xrightarrow{(a,br)}$$



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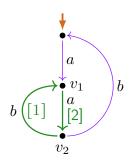
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L3.



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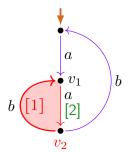
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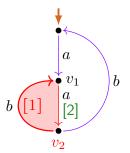
L1. L2. L3.

$$\begin{split} \mathcal{L}(v, \rightarrow_{[n]}, \rightarrow_{\mathsf{br},[>n]}) &\coloneqq \mathsf{subchart induced} \\ \mathsf{by entry steps} \rightarrow_{[n]} \mathsf{from } v \\ \mathsf{followed by branch steps} \rightarrow_{\mathsf{br}} \\ & \mathsf{or entry steps} \rightarrow_{[m]} \mathsf{with } m > n, \\ \mathsf{until } v \mathsf{ is reached again} \end{split}$$



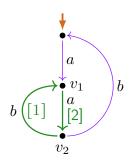
$$\mathcal{L}(v_2, \rightarrow_{[1]}, \rightarrow_{\mathsf{br},[>1]})$$

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 $\mathcal{L}(v_2, \rightarrow_{[1]}, \rightarrow_{\mathsf{br},[>1]})$  is loop subchart

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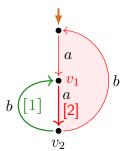
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$$\mathcal{L}(v_1, \rightarrow_{[2]}, \rightarrow_{\mathsf{br},[>2]})$$

loop-branch labeling: marking transitions  $\xrightarrow{a}$  as: • entry steps  $\xrightarrow{\langle a, \lfloor n \rfloor \rangle}$  for  $n \in \mathbb{N}$ , written  $\xrightarrow{a}_{[n]}$ , • branch steps  $\xrightarrow{\langle a, br \rangle}$ , written  $\xrightarrow{a}_{br}$  or  $\xrightarrow{a}$ . Definition A loop-branch labeling is a LEE-witness, if: L1. L2. L3.  $\mathcal{L}(v, \rightarrow_{[n]}, \rightarrow_{\mathsf{br},[>n]}) \coloneqq$  subchart induced by entry steps  $\rightarrow_{[n]}$  from v followed by branch steps  $\rightarrow_{br}$ or entry steps  $\rightarrow_{[m]}$  with m > n, until v is reached again

 $b \underbrace{ \begin{bmatrix} 1 \end{bmatrix} \\ v_1 \\ a \\ v_2 \end{bmatrix} } b$ 

 $\mathcal{L}(v_1, \rightarrow_{[2]}, \rightarrow_{\mathsf{br},[>2]})$  is loop subchart

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 $b \underbrace{[1]}_{v_2} \overset{\bullet}{[2]} b$ 

$$\mathcal{L}(v_2, \rightarrow_{[1]}, \rightarrow_{\mathsf{br},[>1]})$$
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LEE-witness

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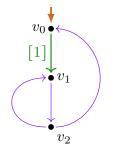
#### Definition

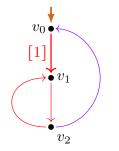
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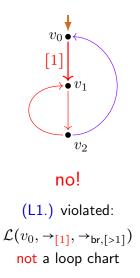
L1.  $\forall n \in \mathbb{N} \forall v \in V \begin{pmatrix} v \to [n] \Rightarrow \mathcal{L}(v, \to_{[n]}, \to_{\mathsf{br}, [>n]}) \\ \text{is a loop subchart} \end{pmatrix}$ . L2. No infinite  $\to_{\mathsf{br}}$  path from start vertex.

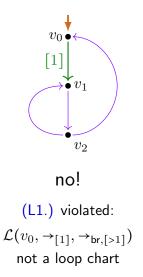
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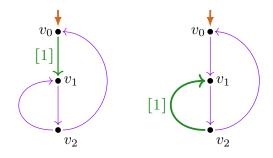
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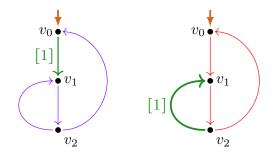






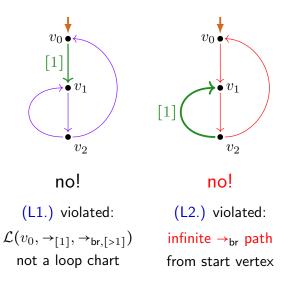
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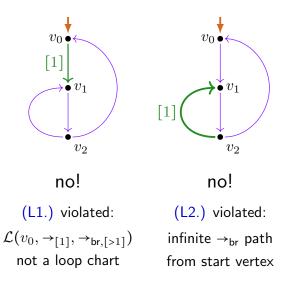
(L1.) violated:  $\mathcal{L}(v_0, \rightarrow_{[1]}, \rightarrow_{\mathsf{br},[>1]})$ not a loop chart

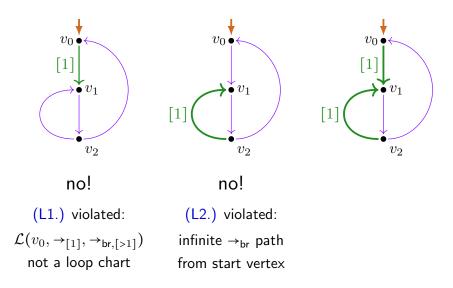


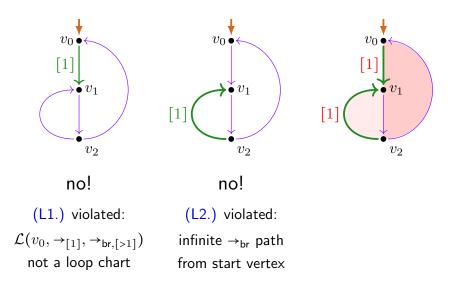
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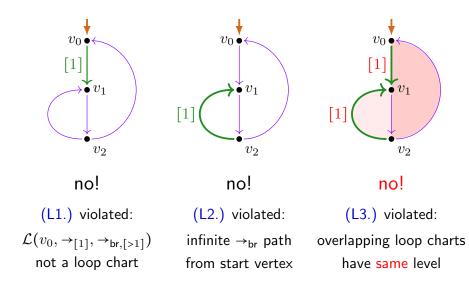
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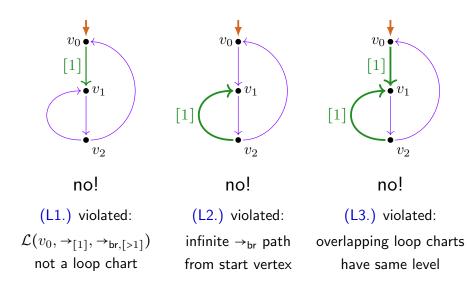


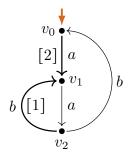


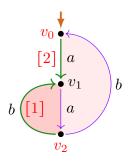












 $\mathcal{L}(v_2, \rightarrow_{[1]}, \rightarrow_{\mathsf{br},[>1]})$  $\mathcal{L}(v_0, \rightarrow_{[2]}, \rightarrow_{\mathsf{br},[>2]})$ 

LEE-witness

loop-branch labeling: marking transitions  $\xrightarrow{a}$  as:

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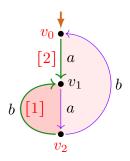
#### Definition

A loop-branch labeling is a LEE-witness, if:

- L1.  $\forall n \in \mathbb{N} \forall v \in V \Big( \begin{array}{c} \mathcal{L}(v, \rightarrow_{[n]}, \rightarrow_{\mathsf{br}, [>n]}) \\ \text{is a loop subchart, or trivial} \\ \end{array} \Big).$
- L2. No infinite  $\rightarrow_{br}$  path from start vertex.

L3.  $\mathcal{L}(w_i, \rightarrow_{[n_i]}, \rightarrow_{\text{br},[>n_i]})$  for  $i \in \{1, 2\}$  loop charts  $\wedge w_1 \neq w_2 \land w_1 \in \mathcal{L}(w_2, ..., ...) \implies n_1 \neq n_2.$ 

$$\begin{split} \mathcal{L}(v, \rightarrow_{[n]}, \rightarrow_{\mathsf{br}, [>n]}) &\coloneqq \mathsf{subchart induced} \\ \mathsf{by entry steps} \rightarrow_{[n]} \mathsf{from } v \\ \mathsf{followed by branch steps} \rightarrow_{\mathsf{br}} \\ \mathsf{or entry steps} \rightarrow_{[m]} \mathsf{with } m > n, \end{split}$$



 $\mathcal{L}(v_2, \rightarrow_{[1]}, \rightarrow_{\mathsf{br},[>1]}) \ \mathcal{L}(v_0, \rightarrow_{[2]}, \rightarrow_{\mathsf{br},[>2]})$ 

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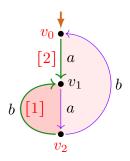
#### Definition

A loop-branch labeling is a layered LEE-witness, if: I-L1.  $\forall n \in \mathbb{N} \forall v \in V \begin{pmatrix} v \rightarrow [n] \Rightarrow \mathcal{L}(v, \rightarrow [n], \rightarrow_{\mathsf{br}, [>n]}) \\ \text{is a loop subchart} \end{pmatrix}$ .

I-L2. No infinite  $\rightarrow_{br}$  path from start vertex.

I-L3.  $\mathcal{L}(w_i, \rightarrow_{[n_i]}, \rightarrow_{\mathsf{br},[>n_i]})$  for  $i \in \{1, 2\}$  loop charts  $\wedge w_1 \neq w_2 \land w_1 \in \mathcal{L}(w_2, \dots, \dots) \Longrightarrow n_1 < n_2.$ 

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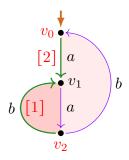
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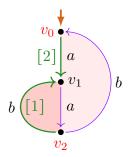
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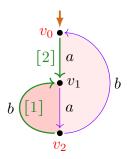
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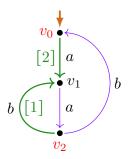
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## LEE versus LEE-witness

Theorem

For every process graph G:

 $\mathsf{LEE}(G) \iff G$  has a  $\mathsf{LEE}$ -witness.

#### LEE versus LEE-witness

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Proof.

 $\Rightarrow$ : record loop elimination

#### LEE versus LEE-witness

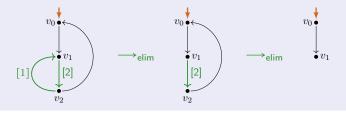
#### Theorem

```
For every process graph G:
```

```
\mathsf{LEE}(G) \iff G has a \mathsf{LEE}-witness.
```

#### Proof.

- $\Rightarrow$ : record loop elimination
- carry out loop-elimination as indicated in the LEE-witness, in *inside-out* direction, e.g.:



# LEE and (layered) LEE-witness

#### Lemma

Every layered LEE-witness is a LEE-witness.

#### Lemma

Every LEE-witness  $\widehat{G}$  of a process graph Gcan be transformed by an effective procedure (cut-elimination-like) into a layered LEE-witness  $\widehat{G}'$  of G.

# LEE and (layered) LEE-witness

#### Lemma

Every layered LEE-witness is a LEE-witness.

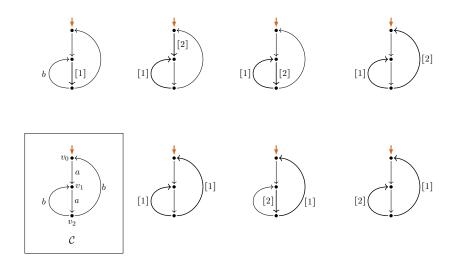
#### Lemma

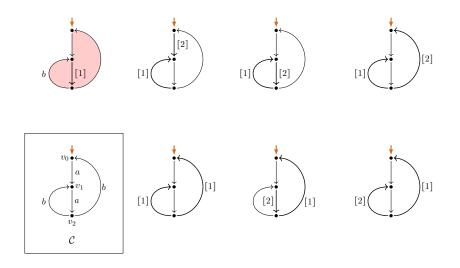
Every LEE-witness  $\widehat{G}$  of a process graph Gcan be transformed by an effective procedure (cut-elimination-like) into a layered LEE-witness  $\widehat{G}'$  of G.

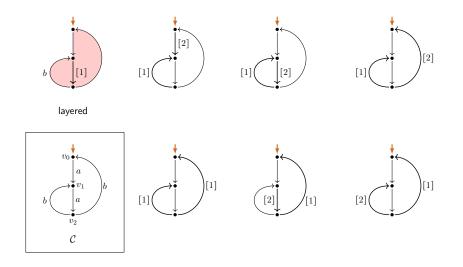
#### Lemma

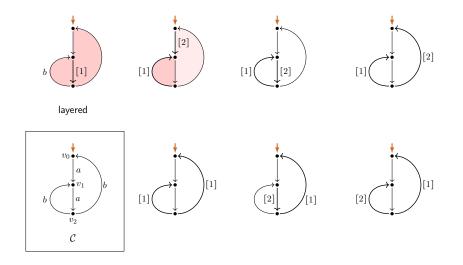
For every process graph G the following are equivalent:

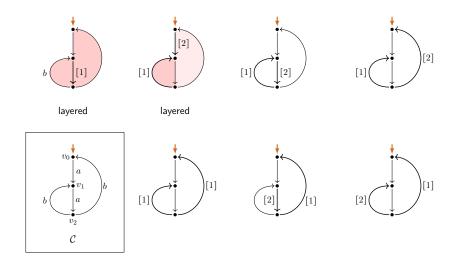
- (i) LEE(G).
- (ii) G has a LEE-witness.
- (iii) G has a layered LEE-witness.

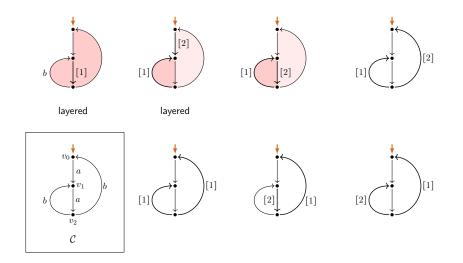


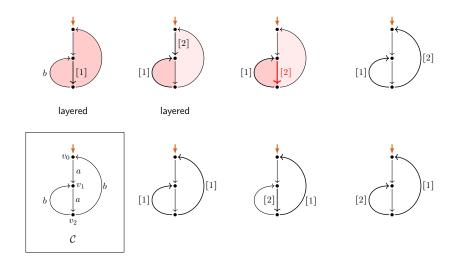


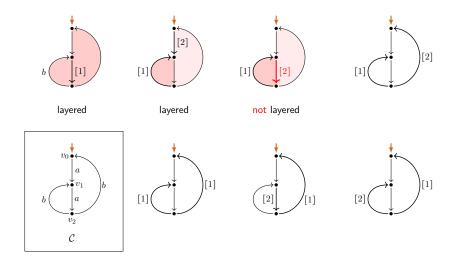


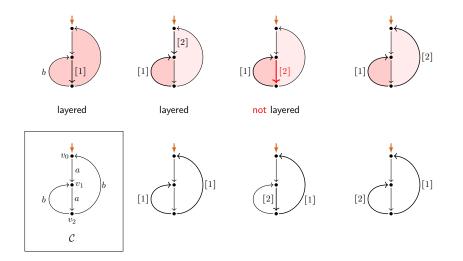


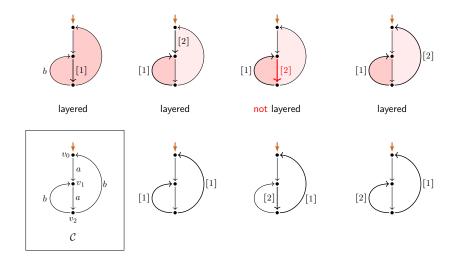


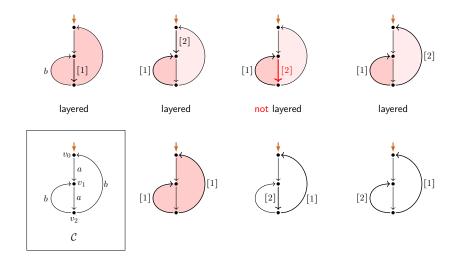


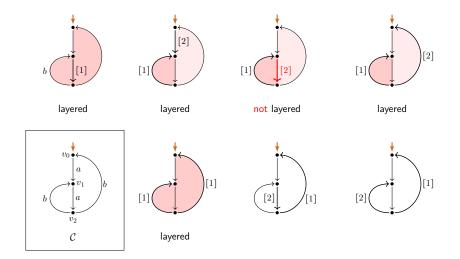


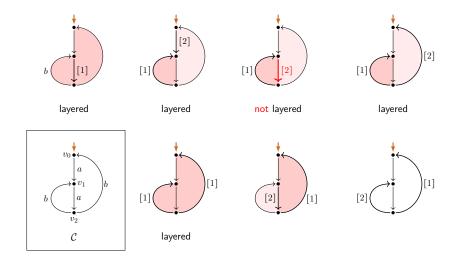


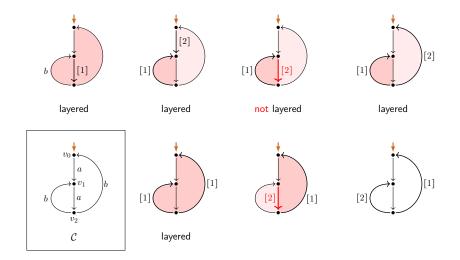


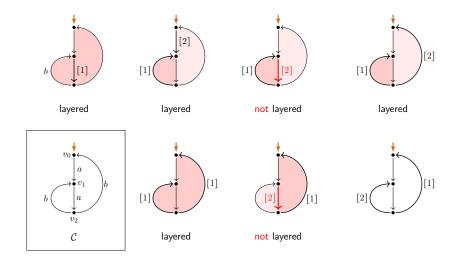


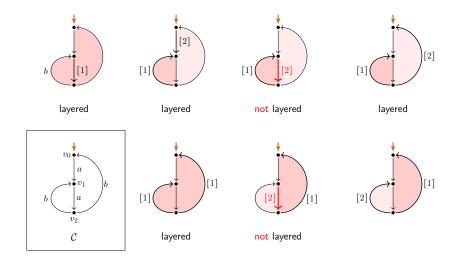


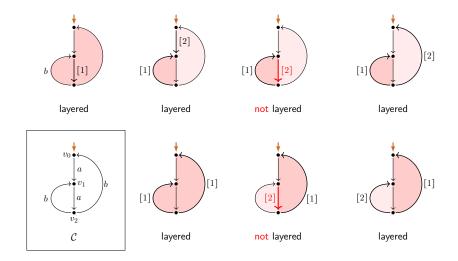


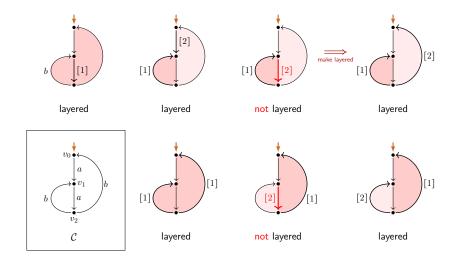


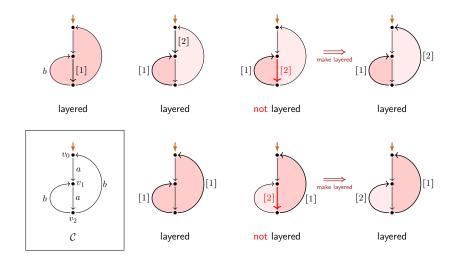


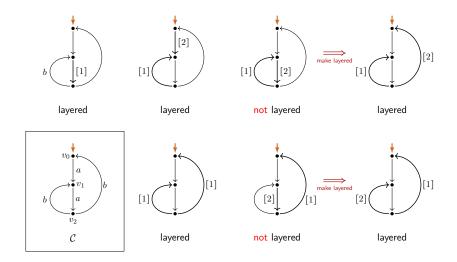










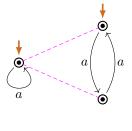


Observation

• LEE is not invariant under bisimulation.

#### Observation

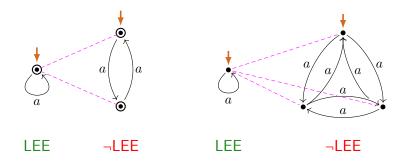
• LEE is not invariant under bisimulation.



LEE ¬LEE

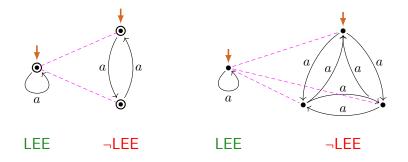
#### Observation

• LEE is not invariant under bisimulation.



#### Observation

- LEE is **not** invariant under bisimulation.
- LEE is not preserved by converse functional bisimulation.



## LEE under functional bisimulation

#### Lemma

(i) LEE is preserved by functional bisimulations:

 $\mathsf{LEE}(G_1) \land G_1 \not\supseteq G_2 \implies \mathsf{LEE}(G_2)$ .

O C-des PI pi Mil Milner's Qs loop-elim LEE LEE-witness collapse readback 1r-less line-up MS interpret collapse readback c d lit C-res

## LEE under functional bisimulation

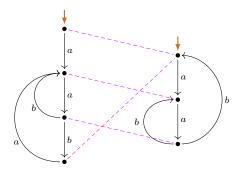
#### Lemma

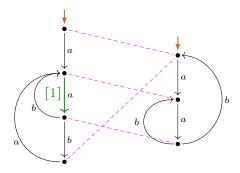
(i) LEE is preserved by functional bisimulations:

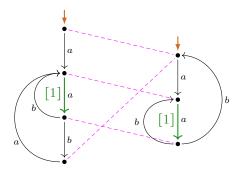
 $\mathsf{LEE}(G_1) \land G_1 \not\supseteq G_2 \implies \mathsf{LEE}(G_2)$ .

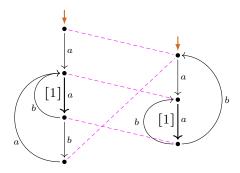
#### Proof (Idea).

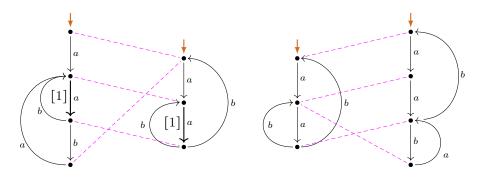
Use loop elimination in  $G_1$  to carry out loop elimination in  $G_2$ .





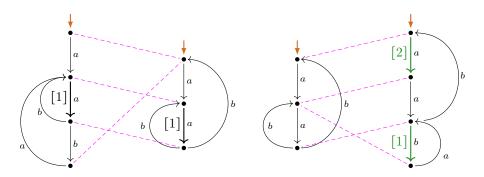






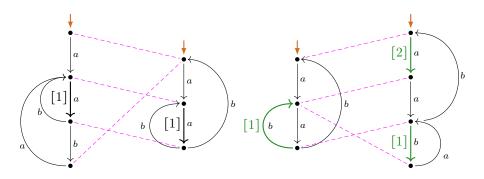
 $\llbracket a(a(b+ba))^*0 \rrbracket_{\mathbf{P}}$ 

 $[(aa(ba)^*b)^*0]_P$ 



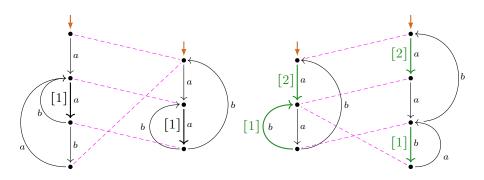
 $\llbracket a(a(b+ba))^*0 \rrbracket_{\mathbf{P}}$ 

 $\llbracket (aa(ba)^*b)^*0 \rrbracket_{\boldsymbol{P}}$ 



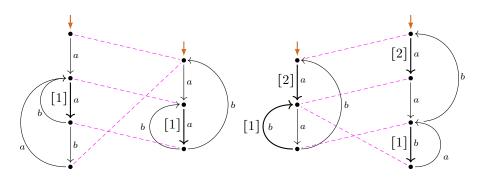
 $\llbracket a(a(b+ba))^*0 \rrbracket_{\mathbf{P}}$ 

 $[(aa(ba)^*b)^*0]_P$ 



 $\llbracket a(a(b+ba))^*0 \rrbracket_{\mathbf{P}}$ 

 $[(aa(ba)^*b)^*0]_{P}$ 



 $\llbracket a(a(b+ba))^*0 \rrbracket_{\mathbf{P}}$ 

 $\llbracket (aa(ba)^*b)^*0 \rrbracket_{\boldsymbol{P}}$ 

# LEE under functional bisimulation

### Lemma

(i) LEE is preserved by functional bisimulations:

 $\mathsf{LEE}(G_1) \land G_1 \not\supseteq G_2 \implies \mathsf{LEE}(G_2)$ .

### Idea of Proof for (i)

Use loop elimination in  $G_1$  to carry out loop elimination in  $G_2$ .

# LEE under functional bisimulation / bisimulation collapse

### Lemma

(i) LEE is preserved by functional bisimulations:

 $\mathsf{LEE}(G_1) \wedge G_1 \simeq G_2 \implies \mathsf{LEE}(G_2)$ .

(ii) LEE is preserved from a process graph to its bisimulation collapse:

 $\mathsf{LEE}(G) \land C$  is bisimulation collapse of  $G \Longrightarrow \mathsf{LEE}(C)$ .

Idea of Proof for (i)

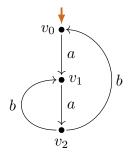
Use loop elimination in  $G_1$  to carry out loop elimination in  $G_2$ .

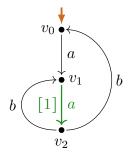
## Readback

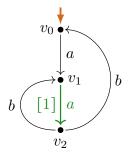
### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$







$$s(v_{0}) = 0^{*} \cdot a \cdot s(v_{1})$$

$$=_{Mil^{-}} a \cdot s(v_{1})$$

$$=_{Mil^{-}} a \cdot (a \cdot (b + b \cdot a))^{*} \cdot 0$$

$$s(v_{1}) = (a \cdot s(v_{2}, v_{1}))^{*} \cdot 0$$

$$=_{Mil^{-}} (a \cdot (b + b \cdot a))^{*} \cdot 0$$

$$s(v_{2}, v_{1}) = 0^{*} \cdot (b \cdot s(v_{1}, v_{1}) + b \cdot s(v_{0}, v_{1}))$$

$$=_{Mil^{-}} 0^{*} \cdot (b \cdot 1 + b \cdot a)$$

$$=_{Mil^{-}} b + b \cdot a$$

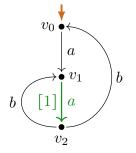
$$s(v_{1}, v_{1}) = 1$$

$$s(v_{0}, v_{1}) = 0^{*} \cdot a \cdot s(v_{1}, v_{1})$$

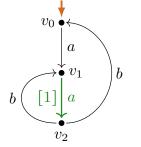
$$= 0^{*} \cdot a \cdot 1$$

$$=_{Mil^{-}} a$$

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

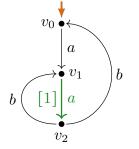


$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



$$s(v_1) = (a \cdot s(v_2, v_1))^* \cdot 0$$

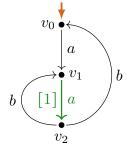
$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



$$s(v_1) = (a \cdot s(v_2, v_1))^* \cdot 0$$

$$s(v_2, v_1) = 0^* \cdot (b \cdot s(v_1, v_1) + b \cdot s(v_0, v_1))$$

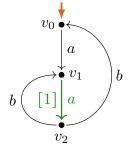
$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



$$s(v_{1}) = (a \cdot s(v_{2}, v_{1}))^{*} \cdot 0$$
  
$$s(v_{2}, v_{1}) = 0^{*} \cdot (b \cdot s(v_{1}, v_{1}) + b \cdot s(v_{0}, v_{1}))$$

 $s(v_1, v_1) = 1$ 

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

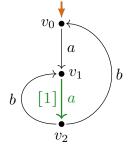


$$s(v_1) = (a \cdot s(v_2, v_1))^* \cdot 0$$

$$s(v_2, v_1) = 0^* \cdot (b \cdot s(v_1, v_1) + b \cdot s(v_0, v_1))$$

$$s(v_1, v_1) = 1 s(v_0, v_1) = 0^* \cdot a \cdot s(v_1, v_1)$$

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



$$s(v_1) = \left(a \cdot s(v_2, v_1)\right)^* \cdot 0$$

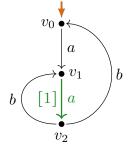
$$s(v_2, v_1) = 0^* \cdot (b \cdot s(v_1, v_1) + b \cdot s(v_0, v_1))$$

$$s(v_1, v_1) = 1$$
  

$$s(v_0, v_1) = 0^* \cdot a \cdot s(v_1, v_1)$$
  

$$= 0^* \cdot a \cdot 1$$

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



$$s(v_1) = (a \cdot s(v_2, v_1))^* \cdot 0$$

$$s(v_2, v_1) = 0^* \cdot (b \cdot s(v_1, v_1) + b \cdot s(v_0, v_1))$$

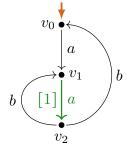
$$s(v_1, v_1) = 1$$
  

$$s(v_0, v_1) = 0^* \cdot a \cdot s(v_1, v_1)$$
  

$$= 0^* \cdot a \cdot 1$$
  

$$=_{\mathsf{Mil}^-} a$$

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



$$s(v_1) = (a \cdot s(v_2, v_1))^* \cdot 0$$

$$s(v_2, v_1) = 0^* \cdot (b \cdot s(v_1, v_1) + b \cdot s(v_0, v_1))$$
  
=<sub>Mil</sub>- 0\* \cdot (b \cdot 1 + b \cdot a)

$$s(v_1, v_1) = 1$$
  

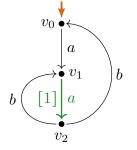
$$s(v_0, v_1) = 0^* \cdot a \cdot s(v_1, v_1)$$
  

$$= 0^* \cdot a \cdot 1$$
  

$$=_{\mathsf{Mil}^-} a$$

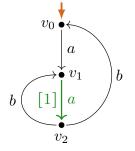
$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$

 $s(v_1) = (a \cdot s(v_2, v_1))^* \cdot 0$ 



$$s(v_{2}, v_{1}) = 0^{*} \cdot (b \cdot s(v_{1}, v_{1}) + b \cdot s(v_{0}, v_{1}))$$
  
$$=_{\mathsf{M}\mathsf{H}^{-}} 0^{*} \cdot (b \cdot 1 + b \cdot a)$$
  
$$=_{\mathsf{M}\mathsf{H}^{-}} b + b \cdot a$$
  
$$s(v_{1}, v_{1}) = 1$$
  
$$s(v_{0}, v_{1}) = 0^{*} \cdot a \cdot s(v_{1}, v_{1})$$
  
$$= 0^{*} \cdot a \cdot 1$$
  
$$=_{\mathsf{M}\mathsf{H}^{-}} a$$

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$



$$s(v_{1}) = (a \cdot s(v_{2}, v_{1}))^{*} \cdot 0$$
  

$$=_{\mathsf{Mil}^{-}} (a \cdot (b + b \cdot a))^{*} \cdot 0$$
  

$$s(v_{2}, v_{1}) = 0^{*} \cdot (b \cdot s(v_{1}, v_{1}) + b \cdot s(v_{0}, v_{1}))$$
  

$$=_{\mathsf{Mil}^{-}} 0^{*} \cdot (b \cdot 1 + b \cdot a)$$
  

$$=_{\mathsf{Mil}^{-}} b + b \cdot a$$
  

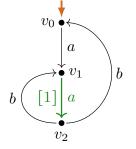
$$s(v_{1}, v_{1}) = 1$$
  

$$s(v_{0}, v_{1}) = 0^{*} \cdot a \cdot s(v_{1}, v_{1})$$
  

$$= 0^{*} \cdot a \cdot 1$$
  

$$=_{\mathsf{Mil}^{-}} a$$

$$s(v_0) = 0^* \cdot a \cdot s(v_1)$$
$$=_{\mathsf{Mil}^-} a \cdot s(v_1)$$





$$s(v_{1}) = (a \cdot s(v_{2}, v_{1}))^{*} \cdot 0$$
  

$$=_{\mathsf{M}\mathsf{i}\mathsf{l}^{-}} (a \cdot (b + b \cdot a))^{*} \cdot 0$$
  

$$s(v_{2}, v_{1}) = 0^{*} \cdot (b \cdot s(v_{1}, v_{1}) + b \cdot s(v_{0}, v_{1}))$$
  

$$=_{\mathsf{M}\mathsf{i}\mathsf{l}^{-}} 0^{*} \cdot (b \cdot 1 + b \cdot a)$$
  

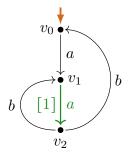
$$=_{\mathsf{M}\mathsf{i}\mathsf{l}^{-}} b + b \cdot a$$
  

$$s(v_{1}, v_{1}) = 1$$
  

$$s(v_{0}, v_{1}) = 0^{*} \cdot a \cdot s(v_{1}, v_{1})$$
  

$$= 0^{*} \cdot a \cdot 1$$
  

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$$s(v_{0}) = 0^{*} \cdot a \cdot s(v_{1})$$

$$=_{Mil^{-}} a \cdot s(v_{1})$$

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$$=_{Mil^{-}} 0^{*} \cdot (b \cdot 1 + b \cdot a)$$

$$=_{Mil^{-}} b + b \cdot a$$

$$s(v_{1}, v_{1}) = 1$$

$$s(v_{0}, v_{1}) = 0^{*} \cdot a \cdot s(v_{1}, v_{1})$$

$$= 0^{*} \cdot a \cdot 1$$

$$=_{Mil^{-}} a$$

### 1-return-less regular expressions

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_{P}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_{P} \right).$$

### 1-return-less regular expressions

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_{P}^{\frac{1}{r} \times -expressible}$ :

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\texttt{lr} \land \star}(A) \left( G \rightleftharpoons \llbracket e \rrbracket_P \right).$$

### 1-return-less regular expressions

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\texttt{tr} \land \texttt{t}}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\texttt{lf} \land \star}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$

Definition (Corradini, De Nicola, Labella (here intuitive version))

A regular expression e is 1-return-less(-under-\*) ( $e \in \text{Reg}^{\pm r \setminus *}(A)$ ) if:

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\texttt{tr} \land \texttt{t}}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\mathsf{l} \mathsf{r} \backslash \star}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$

Definition (Corradini, De Nicola, Labella (here intuitive version))

A regular expression e is 1-return-less(-under-\*) ( $e \in \text{Reg}^{++}(A)$ ) if:

- ▶ for <u>no</u> iteration subexpression f<sup>\*</sup> of e does [[f]]<sub>P</sub> proceed to a process p such that:
  - p has the option to immediately terminate, and
  - p has the option to do a proper step, and terminate later.

• 
$$(a \cdot (1+b))^*$$

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\texttt{tr} \land \texttt{t}}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\mathsf{l} \mathsf{r} \backslash \star}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$

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$$(a \cdot (1+b))^*$$

### 1-return-less regular expressions

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\texttt{tr} \land \texttt{t}}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\texttt{lf} \land \star}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$

Definition (Corradini, De Nicola, Labella (here intuitive version))

A regular expression e is 1-return-less(-under-\*) ( $e \in \text{Reg}^{++}(A)$ ) if:

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  - p has the option to do a proper step, and terminate later.

### 1-return-less regular expressions

#### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\texttt{tr} \land \texttt{t}}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\mathsf{l} \mathsf{r} \backslash \star}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$

Definition (Corradini, De Nicola, Labella (here intuitive version))

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×

p has the option to do a proper step, and terminate later.

• 
$$(a \cdot (1+b))^*$$

• 
$$(a \cdot (0^* + b))^*$$

### 1-return-less regular expressions

#### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\texttt{tr} \land \texttt{t}}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\texttt{lf} \land \star}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$

Definition (Corradini, De Nicola, Labella (here intuitive version))

A regular expression e is 1-return-less(-under-\*) ( $e \in \text{Reg}^{++}(A)$ ) if:

- ▶ for <u>no</u> iteration subexpression f<sup>\*</sup> of e does [[f]]<sub>P</sub> proceed to a process p such that:
  - p has the option to immediately terminate, and

× ×

p has the option to do a proper step, and terminate later.

• 
$$(a \cdot (1+b))^*$$

• 
$$(a \cdot (0^* + b))^*$$

### 1-return-less regular expressions

### Lemma

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$$\bullet \ a \cdot (a \cdot (b + b \cdot a))^* \cdot 0$$

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\ddagger + \lambda_*}$ -expressible:

$$\mathsf{LEE}(G) \implies \exists e \in \mathsf{Reg}^{\mathsf{l} \mathsf{r} \backslash \star}(A) \left( G \nleftrightarrow \llbracket e \rrbracket_P \right).$$

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• 
$$(a^*(b^* + c \cdot 0)^*)^*$$

### Lemma

Process graphs with LEE are  $\llbracket \cdot \rrbracket_P^{\text{1+}}$ -expressible:

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$$(a \cdot (1+b))^*$$
 ×  $(a^*(b^*+c \cdot 0)^*)^*$  ×  
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Non-/Examples of 1-return-less regular expressions

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$$\bullet \ a \cdot (a \cdot (b + b \cdot a))^* \cdot 0 \quad \checkmark$$

×

### l emma

Process graphs with LEE are  $\left\|\cdot\right\|_{\mathcal{D}}^{\frac{1}{2}}$ -expressible:

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×

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#### Theorem

For every process graph G with bisimulation collapse C the following are equivalent:

```
(i) G is \llbracket \cdot \rrbracket_P^{\ddagger \ast}-expressible modulo \leq.
```

```
(ii) LEE(C).
```

- (iii) C has a LEE-witness.
- (iv) C has a layered LEE-witness.

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Milners characterization question:

Q1. Which structural property of finite process graphs characterizes  $\llbracket \cdot \rrbracket_P$ -expressibility modulo  $\Leftrightarrow$ ?

#### Theorem

For every process graph G with bisimulation collapse C the following are equivalent:

- (i) G is  $\llbracket \cdot \rrbracket_P^{\frac{1}{P}}$ -expressible modulo  $\leq$ .
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Milners characterization question restricted:

Q1'. Which structural property of finite process graphs characterizes  $\left[\!\left.\cdot\right]\!\right]_{P}^{\frac{1}{2}+\lambda}$ -expressibility modulo  $\Leftrightarrow$ ?

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Milners characterization question restricted, and adapted:

Q1". Which structural property of collapsed finite process graphs characterizes  $[\![\cdot]]_P^{\texttt{tr}\setminus \star}$ -expressibility modulo  $\Leftrightarrow$ ?

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Answering Milners characterization question restricted, and adapted:

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  - ► The loop-existence and elimination property LEE.

# Characterization of expressibility $r^{\star}$ modulo $\leq$

#### Theorem

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Answering Milners characterization question restricted, and adapted:

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  - ► The loop-existence and elimination property LEE.

Also yields: efficient decision method of  $\left[\cdot\right]_{P}^{\frac{1}{2}}$ -expressibility modulo  $\leq$ .

## Structure constrained finite process graphs

graphs with LEE / a (layered) LEE-witness

- ▶ is closed under ≥
- forth-/back-correspondence with 1-return-less regular expressions

### Structure constrained finite process graphs

graphs with LEE / a (layered) LEE-witness

- $\subseteq$  graphs whose collapse satisfies LEE
- = graphs that are  $\llbracket \cdot \rrbracket_P^{\frac{1}{2}}$ -expressible modulo  $\leq$

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O C-des PI pi Mil Milner's Qs loop-elim LEE LEE-witness collapse readback 1r-less line-up MS interpret collapse readback c d lit C-res

### Structure constrained finite process graphs

- $\llbracket \cdot \rrbracket_P^{\frac{1}{r} \times -expressible graphs}$
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O C-des PI pi Mil Milner's Qs loop-elim LEE LEE-witness collapse readback 1r-less line-up MS interpret collapse readback c d lit C-res

### Structure constrained finite process graphs

### loop-exit palm trees $\subseteq [\cdot]_P^{1+/*}$ -expressible graphs

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# Structure constrained finite process graphs

loop-exit palm trees  $\subseteq [\cdot]_P^{1+/*}$ -expressible graphs

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- ⊊ finite process graphs

#### Benefits of the class of process graphs with LEE:

- ▶ is closed under  $\ge$
- ▶ forth-/back-correspondence with 1-return-less regular expressions

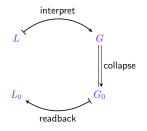
Application to Milner's questions yields partial results:

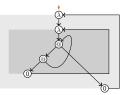
Q1: characterization/efficient decision of  $\llbracket \cdot \rrbracket_P^{\text{tr},\star}$ -expressibility modulo  $\Leftrightarrow$ 

Q2: alternative compl. proof of Mil on 1-return-less expressions (C/DN/L)

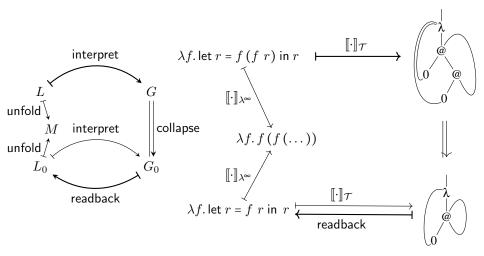
# Maximal sharing of functional programs

(joint work with Jan Rochel)





### maximal sharing: example (fix)



O C-des PI pi Mil Milner's Qs loop-elim LEE LEE-witness collapse readback 1r-less line-up MS interpret collapse readback c d lit C-res

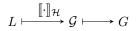
## maximal sharing: the method

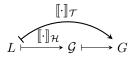


a. higher-order term graph  $\mathcal{G} = \llbracket L \rrbracket_{\mathcal{H}}$ 

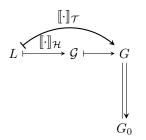


- 1. term graph interpretation  $[\cdot]$ . of  $\lambda_{\text{letrec}}$ -term L as:
  - a. higher-order term graph  $\mathcal{G} = \llbracket L \rrbracket_{\mathcal{H}}$
  - b. first-order term graph  $G = \llbracket L \rrbracket_{\mathcal{T}}$

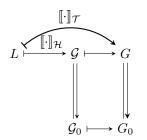




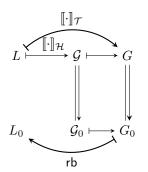
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- 2. bisimulation collapse  $|\downarrow$  of f-o term graph G into  $G_0$



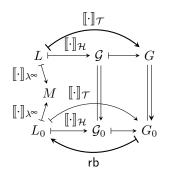
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3. readback rb

of f-o term graph  $G_0$ yielding program  $L_0 = rb(G_0)$ .

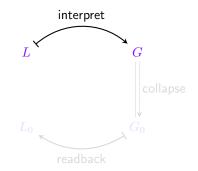


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## interpretation

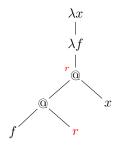


#### running example

 $\begin{array}{ll} \text{instead of:} \\ \lambda f. \, \text{let } r = f\left(f\,r\right) \, \text{in } r & \longmapsto_{\text{max-sharing}} & \lambda f. \, \text{let } r = f\,r \, \text{in } r \\ \text{we use:} \\ \lambda x. \, \lambda f. \, \text{let } r = f\left(f\,r\,x\right) x \, \text{in } r & \longmapsto_{\text{max-sharing}} & \lambda x. \, \lambda f. \, \text{let } r = f\,r\,x \, \text{in } r \\ \\ L & \longmapsto_{\text{max-sharing}} & L_0 \end{array}$ 

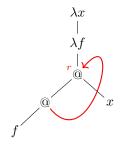
 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 

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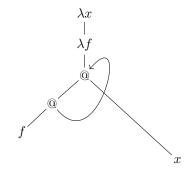
#### syntax tree

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



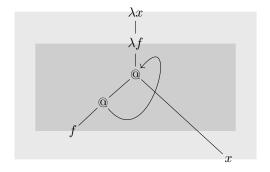
#### syntax tree (+ recursive backlink)

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



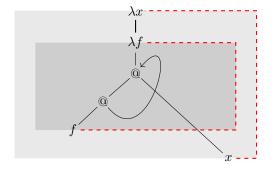
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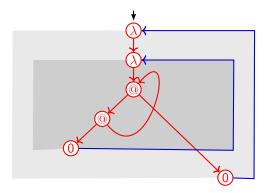
syntax tree (+ recursive backlink, + scopes)

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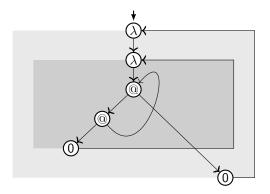
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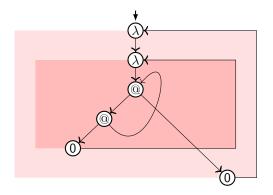
first-order term graph with binding backlinks (+ scope sets)

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



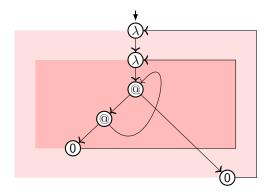
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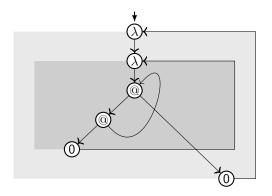
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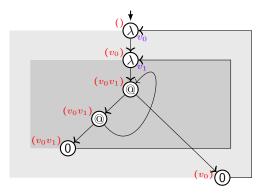
higher-order term graph (with scope sets, Blom [2003])

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



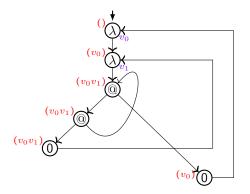
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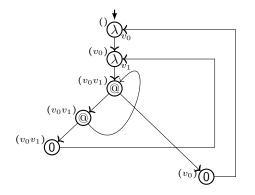
higher-order term graph (with scope sets, + abstraction-prefix function)

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



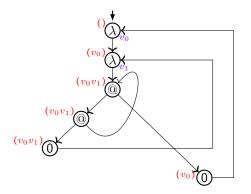
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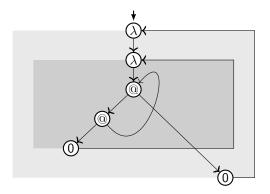
 $\lambda$ -higher-order-term-graph  $\llbracket L_0 \rrbracket_{\mathcal{H}}$ 

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



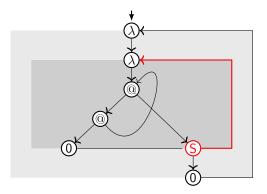
first-order term graph (+ abstraction-prefix function)

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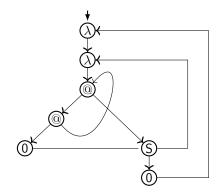
first-order term graph with binding backlinks (+ scope sets)

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



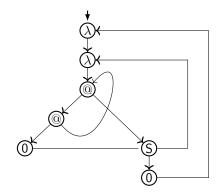
first-order term graph with scope vertices with backlinks (+ scope sets)

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 



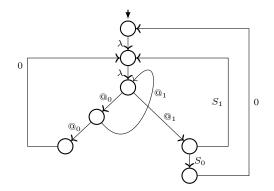
first-order term graph with scope vertices with backlinks

 $L_0 = \lambda x. \lambda f. \text{ let } r = f r x \text{ in } r$ 

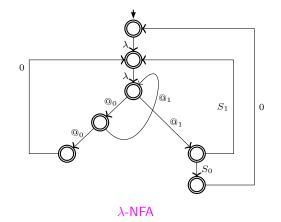


 $\lambda$ -term-graph  $\llbracket L_0 \rrbracket_{\mathcal{T}}$ 

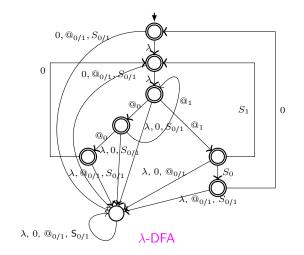
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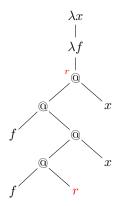


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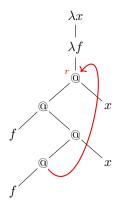
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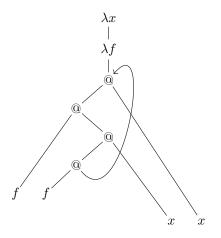
#### syntax tree

 $L = \lambda x. \lambda f.$  let r = f(frx)x in r



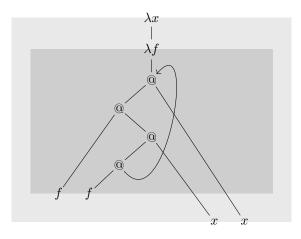
#### syntax tree (+ recursive backlink)

 $L = \lambda x. \lambda f.$  let r = f(frx)x in r



syntax tree (+ recursive backlink)

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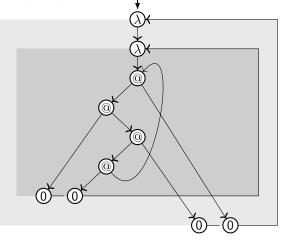


syntax tree (+ recursive backlink, + scopes)

 $L = \lambda x. \lambda f.$  let r = f(frx)x in r

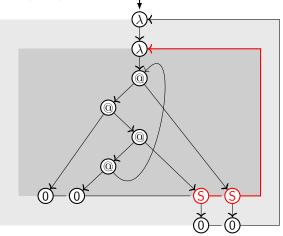
first-order term graph with binding backlinks (+ scope sets)

 $L = \lambda x. \lambda f.$  let r = f(frx)x in r



#### $\lambda$ -higher-order-term-graph $\llbracket L \rrbracket_{\mathcal{H}}$

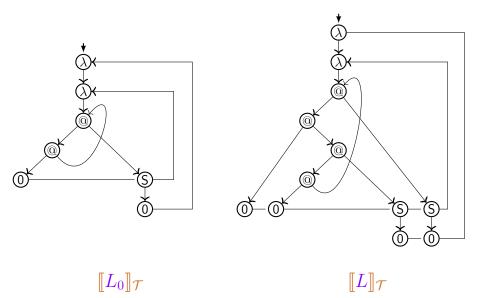
 $L = \lambda x. \lambda f. \text{ let } r = f(frx)x \text{ in } r$ 



first-order term graph with scope vertices with backlinks (+ scope sets)

 $L = \lambda x. \lambda f.$  let r = f(frx)x in r 0  $\bigcirc$ 0

#### $\lambda$ -term-graph $\llbracket L \rrbracket_{\mathcal{T}}$



# interpretation $\llbracket \cdot \rrbracket_{\mathcal{T}}$ : properties (cont.)

interpretation  $\lambda_{\mathsf{letrec}}$ -term  $L \mapsto \lambda$ -term-graph  $\llbracket L \rrbracket_{\mathcal{T}}$ 

- defined by induction on structure of L
- similar analysis as fully-lazy lambda-lifting
- yields eager-scope  $\lambda$ -term-graphs: ~ minimal scopes

#### Theorem

For  $\lambda_{\text{letrec}}$ -terms  $L_1$  and  $L_2$  it holds: Equality of infinite unfolding coincides with bisimilarity of  $\lambda$ -term-graph interpretations:

 $\llbracket L_1 \rrbracket_{\lambda^{\infty}} = \llbracket L_2 \rrbracket_{\lambda^{\infty}} \iff \llbracket L_1 \rrbracket_{\mathcal{T}} \Leftrightarrow \llbracket L_2 \rrbracket_{\mathcal{T}}$ 

# interpretation $\llbracket \cdot \rrbracket_{\mathcal{T}}$ : properties (cont.)

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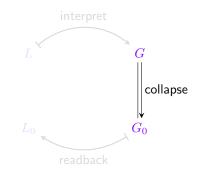
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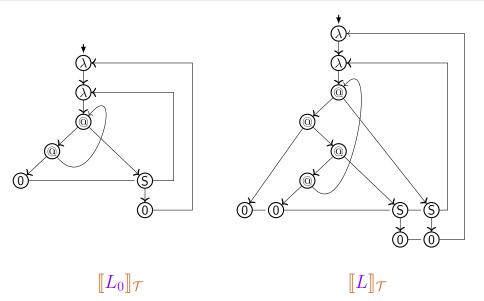
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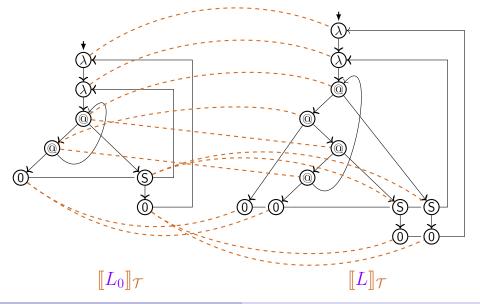
### collapse



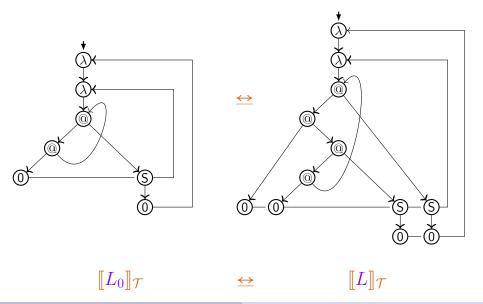
### bisimulation check between $\lambda$ -term-graphs



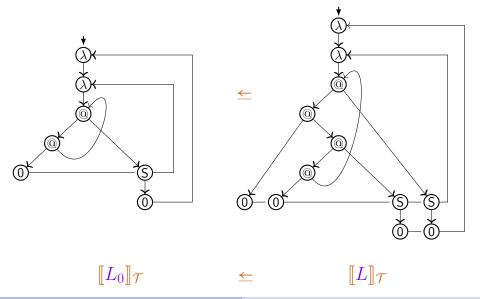
### bisimulation between $\lambda$ -term-graphs



### bisimilarity between $\lambda$ -term-graphs



### functional bisimilarity and bisimulation collapse



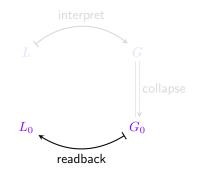
### bisimulation collapse: property

#### Theorem

The class of eager-scope  $\lambda$ -term-graphs is closed under functional bisimilarity  $\Rightarrow$ .

 $\implies$  For a  $\lambda_{ ext{letrec}}$ -term L

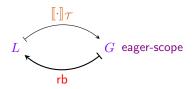
the bisimulation collapse of  $\llbracket L \rrbracket_{\mathcal{T}}$  is again an eager-scope  $\lambda$ -term-graph.



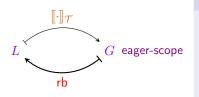
defined with property:



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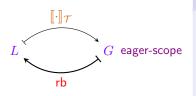
#### Theorem

For all eager-scope  $\lambda$ -term-graphs G:

 $(\llbracket \cdot \rrbracket_{\mathcal{T}} \circ \mathsf{rb})(G) \simeq G$ 

The readback rb is a right-inverse of  $\llbracket \cdot \rrbracket_{\mathcal{T}}$ modulo isomorphism  $\simeq$ .

#### defined with property:



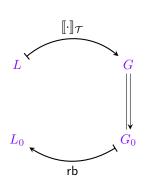
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modulo isomorphism ≃.

idea:

- 1. construct a spanning tree T of G
- 2. using local rules, in a bottom-up traversal of T synthesize L = rb(G)

# maximal sharing: complexity



- 1. interpretation
  - of  $\lambda_{\mathsf{letrec}}$ -term L with |L| = n
  - as  $\lambda$ -term-graph  $G = \llbracket L \rrbracket_T$
  - ▶ in time  $O(n^2)$ , size  $|G| \in O(n^2)$ .
- 2. bisimulation collapse  $|\downarrow$  of f-o term graph G into  $G_0$ 
  - in time  $O(|G|\log|G|) = O(n^2\log n)$
- 3. readback rb

of f-o term graph  $G_0$ yielding  $\lambda_{\text{letrec}}$ -term  $L_0 = \text{rb}(G_0)$ .

• in time  $O(|G|\log|G|) = O(n^2\log n)$ 

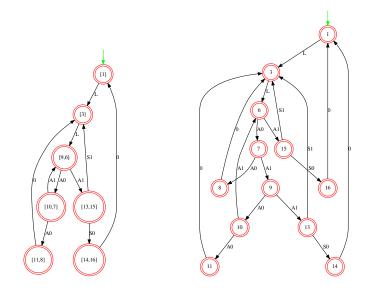
#### Theorem

Computing a maximally compact form  $L_0 = (rb \circ |\downarrow \circ [\![\cdot]\!]_{\mathcal{T}})(L)$  of L for a  $\lambda_{\text{letrec}}$ -term L requires time  $O(n^2 \log n)$ , where |L| = n.

# Demo: console output

```
ian:~/papers/maxsharing-ICFP/talks/ICFP-2014> maxsharing running.l
\lambda-letrec-term:
\lambda x. \lambda f. let r = f(f r x) x in r
derivation:
            ----- 0 ----- 0
            (x f[r]) f (x f[r]) r (x) x
(x) x
(x f[r]) f (f r x)
                ۵) -----
۵) ۸ -----
(x f[r]) f (f r x) x
                                                            (x f[r]) r
                                                                 ---- let
(x f) let r = f (f r x) x in r
                           .....λ
(x) \lambda f. let r = f(f r x) x in r
                                .....λ
() \lambda x. \lambda f. let r = f (f r x) x in r
writing DFA to file: running-dfa.pdf
readback of DFA:
\lambda x, \lambda y, let F = v (v F x) x in F
writing minimised DFA to file: running-mindfa.pdf
readback of minimised DFA:
\lambda x. \lambda y. let F = y F x in F
jan:~/papers/maxsharing-ICFP/talks/ICFP-2014>
                          Clemens Grabmayer
                                       Modeling Terms by Graphs with Structure Constraints
```

# Demo: generated $\lambda$ -NFAs



# Resources (maximal sharing)

- tool maxsharing on hackage.haskell.org
- papers and reports
  - Maximal Sharing in the Lambda Calculus with Letrec
    - ICFP 2014 paper
    - accompanying report arXiv:1401.1460
  - Term Graph Representations for Cyclic Lambda Terms
    - TERMGRAPH 2013 proceedings
    - extended report arXiv:1308.1034
  - Vincent van Oostrom, CG: Nested Term Graphs
    - TERMGRAPH 2014 post-proceedings in EPTCS 183
- thesis Jan Rochel
  - Unfolding Semantics of the Untyped  $\lambda$ -Calculus with letrec
    - Ph.D. Thesis, Utrecht University, 2016

### Comparison results: structure-constrained graphs

Regular expressions under  $\Leftrightarrow_P$ 

*Given:* graph interpretation  $\llbracket \cdot \rrbracket_P$ , studied under bisimulation  $\Leftrightarrow$ 

▶ not closed under  $\rightarrow$ , and  $\leftrightarrow$ , incomplete under  $\leftrightarrow$ 

 $\lambda$ -calculus with letrec under = $_{\lambda^{\infty}}$ 

*Not available:* graph interpretation that is studied under  $\Leftrightarrow$ 

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Defined: class of process graphs with LEE / (layered) LEE-witness

- closed under  $\Rightarrow$  (hence under collapse)
- back-/forth correspondence with 1-return-less expr's
- contains the collapse of a process graph G ⇔ G is []<sup>14</sup>/<sub>P</sub> -expressible modulo ⇔

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Defined: int's  $\llbracket \cdot \rrbracket_{\mathcal{H}} / \llbracket \cdot \rrbracket_{\mathcal{T}}$  as higher-order/first-order  $\lambda$ -term graphs

- closed under  $\Rightarrow$  (hence under collapse)
- ▶ back-/forth correspondence with  $\lambda$ -calculus with letrec
  - efficient translation and readback
  - translation is inverse of readback